## International

 Iger Recifier
# IRDCiP2002-C: 1MHz, 120A, 4-phase Synchronous Buck Converter using iP2002 

## Overview

This reference design is capable of delivering up to 120A at an ambient temperature of $45^{\circ} \mathrm{C}$ if the enclosed heatsink is attached and 250LFM of airflow is provided. Performance graphs and waveforms are provided in figures 1-9. The figures and table in pages 4-7 are provided as a reference design to enable engineers to very quickly and easily design a 4-phase converter. Refer to the data sheet for the controller listed in the bill of materials in order to optimize this design to your specific requirements. A variety of other controllers may also be used, but the design will require layout and control circuit modifications.

## Demoboard Quick Start Guide



## Initial Settings:

The output is set to 1.3 V , but can be adjusted from 0.8 V to 3.3 V by changing the values of R 3 and R 32 according to the following formula:

$$
\mathrm{R} 3=\mathrm{R} 32=(24.91 \mathrm{k} * 0.8) /\left(\mathrm{V}_{\text {OUT }}-0.8\right)
$$

The switching frequency per phase is set to 1 MHz with the frequency set resistor R 4 . This creates an effective output frequency of 4 MHz . The graph in figure 11 shows the relationship between R 4 and the switching frequency per phase. The frequency may be adjusted by changing R4 as indicated; however, extreme changes from the 1 MHz set point may require redesigning the control loop and adjusting the values of input and output capacitors. Refer to the SOA graph in the iP2002 datasheet for maximum operating current at different conditions.

## Procedure for Connecting and Powering Up Demoboard:

1. Apply input voltage ( +12 V ) across VIN and PGND
2. Apply load across VOUT pads and PGND pads
3. Adjust load to desired level. See recommendations below.

## iP2002 Recommended Operating Conditions

(refer to the iP2002 datasheet for maximum operating conditions)
Input voltage: $6.5-12 \mathrm{~V}$
Output voltage: $0.8-3.3 \mathrm{~V}$
Switching Freq: 1 MHz per phase, 4 MHz effective output frequency.
Output current:
The reference design is capable of delivering up to 120 A at an ambient temperature of $45^{\circ} \mathrm{C}$ if the enclosed heatsink is attached and 250LFM of airflow is provided. With a heatsink and no airflow, the reference board is capable of delivering 110 A at $25^{\circ} \mathrm{C}$ ambient. With 250 LFM and no heatsink, the reference board is capable of delivering 100 A at $25^{\circ} \mathrm{C}$ ambient.


Fig. 1: Power Loss vs. Current


Fig. 2: Efficiency vs. Current


Fig. 3: Bode Plot


Fig: 4: Input Voltage Ripple Waveform


Fig. 5: Output Voltage Ripple Waveform

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Fig. 6: Output Voltage Accuracy vs. Current


Fig. 7: Power Up Waveform


Fig. 8: Power Down Waveform


Fig 9: Short Circiut Condition Waveform

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## Adjusting the Over-Current Limit

R5, R7, R8 \& R9 are the resistors used to adjust the over-current trip point. The trip point is a function of the controller and corresponds to the per phase output current indicated on the x-axis of Fig. 10. For example, selecting 2.7k resistors will set the trip point of each phase to 49.5 A . (Note: Fig. 10 is based on $\mathrm{P} 2002 \mathrm{~T}_{\mathrm{BLK}}=125^{\circ} \mathrm{C}$. The trip point will be higher than expected if the reference board is cool and is being used for short circuit testing.)


Fig. 10: $\mathrm{R}_{\text {ISEN }}$ vs. Current (per Phase)


Fig. 11: R4 vs. Frequency (per Phase)


Fig. 12: Component Placement Top Layer


## Heatsink Notes:

1) Always use the supplied Bergquist Gap Pad ${ }^{T M}$ A2000 thermal interface material with heatsink.
2) Torque $4 x \# 2-56$ machine screws to $15 \pm 1$ in-oz.
3) The heatsink is optimized for 250 LFM with unconfined airflow. Performance will improve with more airflow or confined airflow.
4) Airflow direction should be parallel to fins for maximum performance.

Fig. 13: Heatsink Specificationss


Fig. 14: Reference Design Schematic

| Quantity | Designator | Type 1 | Type 2 | Value 1 | Value 2 | Tolerance | Package | Manufac 1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | C1 | capacitor | NPO | 560pF | 50 V | 5\% | 0805 | ROHM |
| 14 | $\begin{gathered} \text { C10, C11, C12, C13, C14, C27, C3, C4, C46, } \\ \text { C5, C6, C7, C8, C9 } \end{gathered}$ | capacitor | X5R | 10.0uF | 16 V | 10\% | 1206 | Murata |
| 8 | C15, C16, C17, C18, C19, C20, C21, C22 | capacitor | X5R | 100uF | 6.3 V | 20\% | 1210 | TDK |
| 2 | C2, C28 | capacitor | X5R | 10.0uF | 6.3 V | 10\% | 1206 | TDK |
| 1 | C25 | capacitor | NPO | 15.0pF | 50 V | 5\% | 0805 | ROHM |
| 1 | C26 | capacitor | NPO | 220pF | 50 V | 5\% | 0805 | Phicomp |
| 31 | C30, C31, C32, C33, C42, C43, C44, C45, C47, R22, R24, R26, R28, R29, R30, R36, SHORT, SHORT1, | open | - | - | - | - | - | - |
| 1 | C34 | capacitor | X7R | 0.100uF | 50 V | 10\% | 0805 | ROHM |
| 4 | C35, C36, C37, C38 | capacitor | X5R | 0.22uF | 6.3 V | 10\% | 0603 | TDK |
| 3 | C39, C40, C41 | capacitor | polymer | 330uF | 16 V | 20\% | SMD | Panasonic |
| 2 | D1, D2 | diode | general purpose | 200 V | 600 mA | - | sot23 | Central semiconductor |
| 4 | HN1, HN2, HN3, HN4 | hardware | hexnut | 4-40 | - | - | - | Building Fasteners |
| 4 | L1, L2, L3, L4 | inductor | ferrite | 0.30 uH | 36A | 20\% | SMT | Panasonic |
| 2 | R1, R4 | resistor | thick film | 20.0 K | 1/8W | 1\% | 0805 | KOA |
| 4 | R10, R11, R12, R13 | resistor | thick film | 0 | 1/8W | <50m | 0805 | ROHM |
| 8 | R16, R17, R18, R19, R21, R23, R25, R27 | resistor | thick film | 10.0K | 1/10W | 1\% | 0603 | KOA |
| 2 | R2, R31 | resistor | thick film | 24.9 K | 1/8W | 1\% | 0805 | KOA |
| 2 | R3, R32 | resistor | thick film | 40.2K | 1/8W | 1\% | 0805 | KOA |
| 1 | R35 | resistor | thick film | 20 | 1/8W | 1\% | 0805 | KOA |
| 4 | R5, R7, R8, R9 | resistor | thick film | 2.74 K | 1/8W | 1\% | 0805 | KOA |
| 1 | R6 | resistor | thick film | 499 | 1/8W | 1\% | 0805 | KOA |
| 8 | SC1, SC2, SC3, SC4, SC5, SC6, SC7, SC8 | hardware | hexnut | 10-24 | - | - | - | McMaster Carr |
| 4 | ST1, ST2, ST3, ST4 | hardware | stand off | 4-40 | 2 | - | alumininum | Keystone |
| 8 | TC1, TC2, TC3, TC4, TC5, TC6, TC7, TC8 | hardware | machine screw | 10-24 | 3/4 | - | - | McMaster Carr |
| 1 | U1 | ISL6558 | PWM controller | 4.5-5.5V | 0.8-5V | - | 16 Ld SOIC | Intersil |
| 4 | U2, U3, U4, U5 | iP2002 | BGA unit | 5-12V | 30A | - | $11 \mathrm{~mm} \times 11 \mathrm{~mm}$ | International Rectifier |
| 1 | U6 | LM1117 | LDO linear regulator | 5.0 V | 800 mA | - | TO-252 | National Semiconductor |

Table 1: Reference Design Bill of Materials
Refer to the following application notes for detailed guidelines and suggestions when implementing iPOWIR Technology products:

## AN-1028: Recommended Design, Integration and Rework Guidelines for International Rectifier's iPOWIR Technology BGA Packages

This paper discusses the assembly considerations that need to be taken when mounting iPOWIR BGA's on printed circuit boards. This includes soldering, pick and place, reflow, inspection, cleaning and reworking recommendations.

## AN-1029: Optimizing a PCB Layout for an iPOWIR Technology Design

This paper describes how to optimize the PCB layout design for both thermal and electrical performance. This includes placement, routing, and via interconnect suggestions.

## AN-1030: Applying iPOWIR Products in Your Thermal Environment

This paper explains how to use the Power Loss and SOA curves in the data sheet to validate if the operating conditions and thermal environment are within the Safe Operating Area of the iPOWIR product.

## AN-1047: Graphical solution for two branch heatsinking Safe Operating Area

Detailed explanation of the dual axis SOA graph and how it is derived.

> Use of this design for any application should be fully verified by the customer. International Rectifier cannot guarantee suitability for your applications, and is not liable for any result of usage for such applications including, without limitation, personal or property damage or violation of third party intellectual property rights.

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